

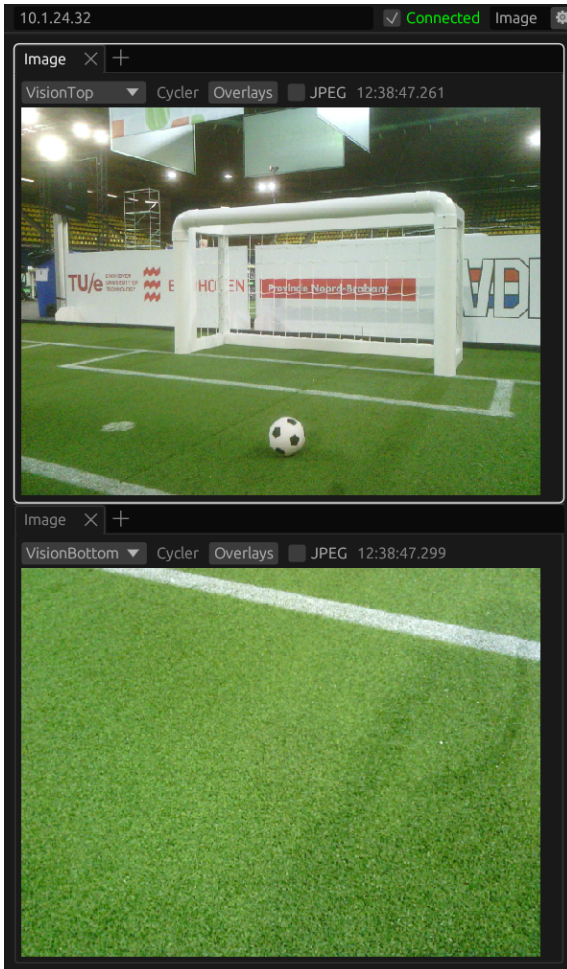
# HULKs

**RoboCup SPL Team • TU Hamburg, Germany**

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# Shared Autonomy Challenge



- expand our existing debug tooling twix
  - ▶ accept controller inputs
  - ▶ override of the robot's path planning
- train team members to play looking through NAO camera